6TH SEM./ELECTRICAL / 2024(S)

Control System Engineering Th-3

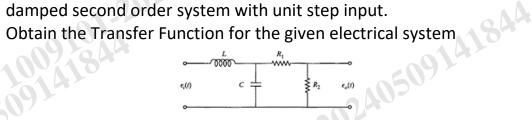
Full Marks: 80

Time- 3 Hrs

2 x 10

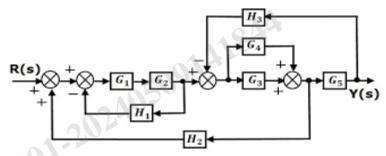
Answer any five Questions including Q No.1& 2 Figures in the right hand margin indicates marks & Use Calculator

- Answer All questions 1.
 - How do you define Transfer Function? a.
 - b. Define Signal Flow Graph (SFG) & write two properties of SFG.
 - Write the effect of Negative feedback in control system. c.
 - d. How do you mean by **Order** and **Type** of a system?
 - State the Mason's gain formula. e.
 - f. What is the main objective of Root-Locus analysis Technique?
 - How do you define relative stability? g.
 - Write the effect of adding poles to closed loop control system. h.
 - i. Give two disadvantages of closed loop control over open loop control system.
 - 141844 Define Peak Time and settling time. **i**.
- 2. Answer Any Six Questions
 - Derive the expression for peak time and setting time for the under a. damped second order system with unit step input.
 - b.



- Explain details of PD controller used in control system.
- 9101-20249 d. Obtain the Transfer Function of a given system using Block Diagram Reduction Technique.

6 x 5



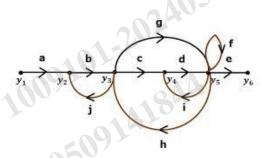
- Explain details of Nicholas Chart used in control system. e.
- f. State difference between open loop and closed loop control system.
- Write short note on Constant M and N circle in brief. g

3

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- Describe construction and working principle of Synchros. Also 10 explain how it is used in servo application.
 - Obtain the closed loop transfer function of the system C(S)/R(S) 10 using Masson's gain formula



5 Sketch the Root-Locus of the system whose transfer function is 10 9141844 given by

$$G(s)H(s) = \frac{K}{s(s+3)(s+5)}$$

Describe with neat block diagram the working of armature 10 controlled DC motor as a control system. The open loop transfer function of the plant is 10 10(c + 2)

$$G(s)H(s) = \frac{10(s+2)}{s^2(s+10)}$$

Use Bode Plot, Find the Gain Margin and Phase Margin.